

PATENT APPLICATION

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Serial No. 09/841,915

Applicant: Dan Alan Preston and Robert Pierce Lutter

Group: 2816

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**INFORMATION DISCLOSURE CITATION
FORM PTO-1449 (Modified)**

OTHER DOCUMENTS

Exam Init	Ref	(Including Author, Title, Date, Pertinent Pages, etc.)
<u>PN</u>	_____	Product description of Raytheon RT Secure, "Embedded Hard Real-Time Secure Operating System", Copyright 2000, pages 1-2.
<u>PN</u>	_____	Product description of Raytheon RT Secure, Copyright 2001, pages 1-2.
<u>PN</u>	_____	Product description of Raytheon RT Secure, "Development Environment", Copyright 2001, pages 1-2.
<u>PN</u>	_____	Product description of Raytheon Electronic Systems (ES), Copyright 2002, pages 1-2.
<u>PN</u>	_____	H. Chung, L. Ojeda, and J. Borenstein, "Sensor Fusion for Mobile Robot Dead-reckoning with a Precision-calibrated Fiber Optic Gyroscope", 2001 IEEE International Conference on Robotics and Automation, Seoul, Korea, May 21-26, pages 1-6.
<u>PN</u>	_____	A. Das, R. Fierro, V. Kumar, J. Ostrowski, J. Spletzer, and C. Taylor, "A Framework for Vision Based Formation Control", IEEE Transactions on Robotics and Automation, Vol. XX, No. Y, 2001, pages 1-13.
<u>PN</u>	_____	J. Takezaki, N. Ueki, T. Minowa, H. Kondoh, "Support System for Safe Driving - A Step Toward ITS Autonomous Driving -", Hitachi Review, Vol. 49, No. 3, 2000, pages 1-8.
<u>PN</u>	_____	S.G. Goodridge, "Multimedia Sensor Fusion for Intelligent Camera Control and Human-Computer Interaction", Dissertation submitted to the Graduate Faculty of North Carolina State University in partial fulfillment of the requirements for the degree of Doctor of Philosophy in Electrical Engineering, Raleigh, NC, 1997, pages 1-5.
<u>PN</u>	_____	M. Chantler, G. Russel, and R. Dunbar, "Probabilistic Sensor Fusion for Reliable Workspace Sensing", pages 1-14.
<u>PN</u>	_____	ISIS Project: Sensor Fusion, Linkoping University Division of Automatic Control and Communication Systems in cooperation with SAAB (Dynamics and Aircraft), 18 pages.
<u>PN</u>	_____	Hitachi Automated Highway System (AHS), Automotive Products, Hitachi, Ltd., Copyright 1994-2002, 8 pages.
<u>PN</u>	_____	Vehicle Dynamics Lab, University of California, Berkeley, funded by BMW, current members: D. Caveney and B. Feldman, "Adaptive Cruise Control", 17 pages.
<u>PN</u>	_____	Counterair: The Cutting Edge, Ch. 2 "The Evolutionary Trajectory The Fighter Pilot-Here to Stay?" AF2025 v3c8-2, December 1996, pages 1-7.



<u>Exam</u>	<u>Ref</u>	<u>Including Author, Title, Date, Pertinent Pages, etc.</u>
<u>Init</u> <u>JN</u>	—	Counterair: The Cutting Edge, Ch. 4 "The Virtual Trajectory Air Superiority without an "Air" Force?" AF2025 v3c8-4, December 1996, pages 1-12.
<u>JN</u>	—	TNO FEL Annual Review 1998: Quality works, 16 pages.
<u>JN</u>	—	Boeing News Release, "Boeing Demonstrates JSF Avionics Multi-Sensor Fusion", Seattle, WA, May 9, 2000, pages 1-2.
<u>JN</u>	—	Boeing Statement, "Chairman and CEO Phil Condit on the JSF Decision", Washington, D.C., October 26, 2001, pages 1-2.
<u>JN</u>	—	Ada 95 Transition Support - Lessons Learned, Sections 3, 4, and 5, CACI, Inc. -Federal, November 15, 1996, 14 pages.
<u>JN</u>	—	Joint Strike Fighter Terrain Database, ets-news.com "Simulator Solutions" 2002, 3 pages.
<u>JN</u>	—	MSRC Redacted Proposal, 3.0 Architecture Development, pages 1-43.
<u>JN</u>	—	Powerpoint Presentation by Robert Allen - Boeing Phantom Works entitled "Real-Time Embedded Avionics System Security and COTS Operating Systems", Open Group Real-Time Forum, July 18, 2001, 16 pages.
<u>JN</u>	—	Green Hills Software, Inc., "The AdaMULTI 2000 Integrated Development Environment", Copyright 2002, 7 pages.

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